



Working Group 4 VLBI Data Structures

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From the IVS website:

The Working Group will **examine the data structure currently used** in VLBI data processing and **investigate what data structure is likely to be needed in the future**.

It will **design a data structure that meets current and anticipated requirements** for individual VLBI sessions including a cataloging, archiving and distribution system.

Further, it will **prepare the transition capability** through conversion of the current data structure as well as **cataloging and archiving software** to the new system.





Mk3 database. Currently 30+ years old. Used to archive and transmit IVS sessions.

A product of its time:

- Designed to run on systems with 20k (!!) memory
- Designed before Fortran had strings

Furthermore...

- Hard to port
- Slow
- Baseline oriented \rightarrow Tremendous redundancy
- Theoretical and observation data mixed.
- Limited user community (20 users?)





Mk3 database.

In spite of its flaws, it has served us well.

- Lasted 30 years—testament to good design.
- Self describing data format.
- Can add new datatypes.





- 0. Handle current and anticipated VLBI data.
- 1. Reduce redundancy
- 2. Ease of access
- 3. Flexibility
- Separation of "observations" from "models" and "theory"
- 5. Ability to access data at different levels of abstraction
- 6. Ability to easily access most common parts of the data
- 7. Consistency
- 8. Completeness ???





- 1. How should data be organized within a session?
- 2. How should data be stored? (Related to ease of access)
- 3. How should data be organized across sessions?
- 4. What impact do these choices have on data flow?





Current database format has two types of data:

- 1. Session data (type 1-lcodes). Scope= entire session
 - A. Stations
 - B. Sources
 - C. Correlator
 - D. ...





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- 1. Session data (type 1-lcodes). Scope= entire session
 - A. Stations
 - B. Sources
 - C. Correlator
 - D. ...
- 2. Observation data (type 2&3 lcodes). Scope = observation
 - A. Observables
 - B. Ambiguities and Editing
 - C. Station Az-El
 - D. Loading corrections
 - E. Calibrations
 - F. EOP
 - G. ...





- 1. Many (most?) of the type 2&3 lcodes are really scan and station dependent, and not observation dependent:
 - A. Station Az-El
 - B. Loading corrections
 - C. Calibrations
 - D. Atmospheric delay
- 2. Others are only scan dependent:
 - A. Source
 - B. EOP

This makes the data tremendously redundant.



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NVI, inc.	

#Stats	#Scans		
2	366		
3	232		
4	158		
5	71		
6	35		
7	0		



×	
NVI, inc.	

#Stats	#Scans	scans*stats	
2	366	732	
3	232	696	
4	158	632	
5	71	355	
6	35	210	
7	0	0	
Total		2625	



×	
NVI, inc.	

#Stats	#Scans	scans*stats	#BL	
2	366	732	1	
3	232	696	3	
4	158	632	6	
5	71	355	10	
6	35	210	15	
7	0	0	21	
Total		2625		



#Scans	scans*stats	#BL	#BL*2*#scans
366	732	1	732
232	696	3	1392
158	632	6	1896
71	355	10	1420
35	210	15	1050
0	0	21	0
	2625		6490
	#Scans 366 232 158 71 35 0	#Scans scans*stats 366 732 232 696 158 632 71 355 35 210 0 0 2625 35	#Scans scans*stats #BL 366 732 1 232 696 3 158 632 6 71 355 10 35 210 15 0 0 21 2625 10 15

2xNumber of observations

NVI, INC.



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NVI, inc	Z. 🔪

#Stats	#Scans	scans*stats	#BL	#BL*2*#scans
2	366	732	1	732
3	232	696	3	1392
4	158	632	6	1896
5	71	355	10	1420
6	35	210	15	1050
7	0	0	21	0
Total		2625		6490
Redundancy				2.47



Redundancy of RDV73



RDV73				
#Stats	#Scans	scans*stats	#BL	#BL*2*#scans
2	134	268	1	268
3	149	447	3	894
4	55	220	6	660
5	42	210	10	840
6	30	180	15	900
7	24	168	21	1008
8	33	264	28	1848
9	34	306	36	2448
10	40	400	45	3600
11	60	660	55	6600
12	39	468	66	5148
13	22	286	78	3432
14	16	224	91	2912
15	11	165	105	2310
Total		4266		32868
Redundancy				7.70





#Stats	#Scans	scans*stats	#BL	#BL*2*#scans
2	164	328	1	328
3	36	108	3	216
4	138	552	6	1656
5	423	2115	10	8460
6	725	4350	15	21750
7	1282	8974	21	53844
8	1377	11016	28	77112
9	1391	12519	36	100152
10	533	5330	45	47970
11	50	550	55	5500
12	9	108	66	1188
13	0	0	78	(
Total		45950		318176
Redundancy				6.92



Redundancy of Stat32_6_2p1D0In



#Stats	#Scans	scans*stats	#BL	#BL*2*#scans
2	431	862	1	862
3	261	783	3	1566
4	145	580	6	1740
5	80	400	10	1600
6	49	294	15	1470
7	15	105	21	630
8	6	48	28	336
9	34	306	36	2448
10	97	970	45	8730
11	200	2200	55	22000
12	232	2784	66	30624
13	362	4706	78	56472
14	516	7224	91	93912
15	596	8940	105	125160
16	601	9616	120	144240
17	683	11611	136	185776
18	639	11502	153	195534
19	274	5206	171	93708
20	82	1640	190	31160
21	10	210	210	4200
22	0	0	231	0
Total		69987		1002168
Redundancy				14.32





Introduce two new types of data:

- 1. Station-scan data depends only on the station and the scan.
- 2. Scan data depends only on the scan.

This requires modest additional bookkeeping:1. A table that connects observations to scans.2. A table that connects scans to stations.





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We could do this using the *present* Mark3 database format.









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I recommend using NetCDF. This also makes it possible to access sub-sets of the data.





- 1. Meets stated goals.
- 2. Self-describing data format.
- 3. Large user community.
- 4. Many tools.
- 5. Well established conventions.
- 6. Flexible.



A NetCDF file can contain an arbitrary number of arrays. The arrays can differ in dimensions and type (byte, short, integer, real, double). The arrays can have attributes like name, unit, long-name, description associated with them.





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This would meet the design goals of accessibility and speed.





The Mark3 database format was designed so that *all* data pertaining to a session resides in one file.

Addvantage: "one-stop-shopping".

Disadvantages:

- 1. Anytime anything changes—calibrations, ambiguities, models—you need a new version of the database.
- 2. Anytime something is added to the database, you need a new version of the database.
- 3. The database now contains lots of obsolete information that is no longer used.





Proposal: Gather data that is similar in scope, origin, physical effect, frequency of change. Store in its own file.





- Proposal: Gather data that is similar in scope, origin, physical effect, frequency of change. Store in its own file.
- 1. Experiment info: everything known about experiment beforehand.
- 2. Atmospheric delay
- 3. Met data
- 4. Calibrations
- 5. Physical and geophysical effects calculable beforehand: relativity, tidal ocean loading, etc.
- 6. Physical and geophysical effects calculable afterwards: atmosphere loading, hydrological loading, etc.
- 7. Observables and commonly used observation related data.
- 8. Editing and Ambiguity
- 9. Less commonly used observation related data





Advantages:

- 1. Items that are not expected to change are separated from items that may change.
- 2. Data is separated from models.
- 3. This approach lends itself to building up the session piece by piece.
- 4. We delay discussion of what the VLBI2010 observable format should look like.
- 5. Commonly used data is separated from less commonly used data.
- 6. This enables easy testing of new models.
- 7. As models improve, they can be easily incorporated.





Corresponding to a database is a wrapper. This is a special file that contains pointers to the associated data files:

R1345.wrp ! Standard IVS session. !More info about what is in here. R1345_sess_GSFC_0001.nc R1345_atm_GSFC_0001.nc R1345_srcmap_GSFC_0001.nc

... R1345_obsc_HAYS_0001.nc R1345_obsu_HAYS_0001.nc R1345_amed_GSFC_0001.nc !NMF mapping function
!Source maps to use.





- 1. Can specify "IVS-standard" session.
- 2. Can incorporate alternative models by replacing a generating alternative NetCDF file and pointing to it in the wrapper file. E.g.

R1345_atm_GSFC_0001.nc →R1345_atm_VIEN_001.nc

- 3. Researchers can use their own "private" wrappers to test alternative models.
- 4. Groups can swap editing and ambiguity information.
- 5. Can easily add new data types.
- 6. Can use this to preserve history of processing.





- Solicit feedback
- Refine approach
- Write detailed design document
- Write software to convert from MK3 to new format.
 - I have written a routine that converts a subset of a Mark3 database to NetCDF.
- Write software to make new format from scratch.